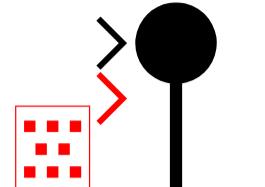
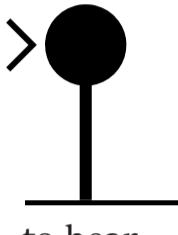


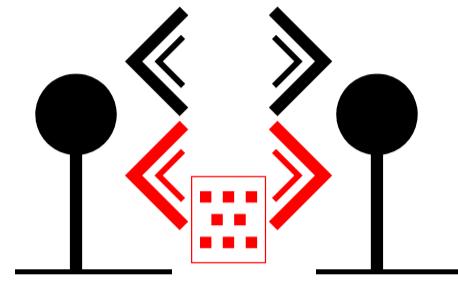
to speak



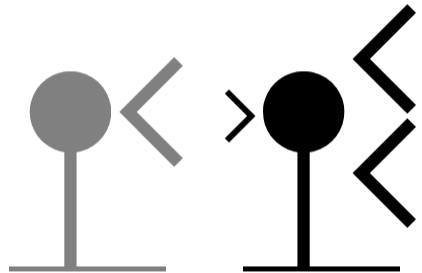
to hear through
an apparatus



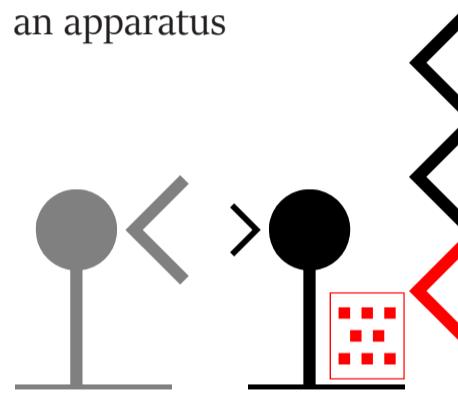
to hear



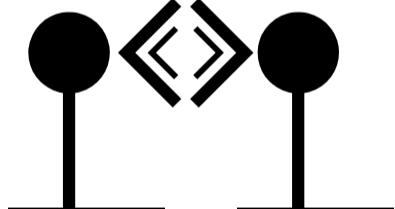
to correspond through
an apparatus



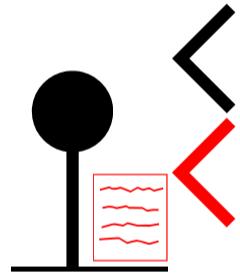
to translate



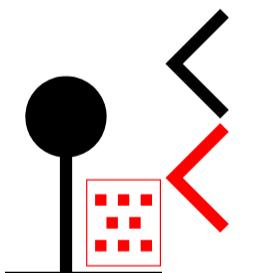
to translate another's speech
through an apparatus



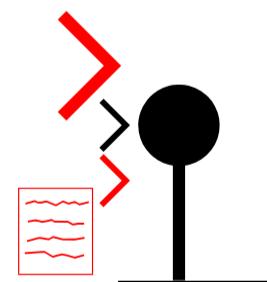
to correspond



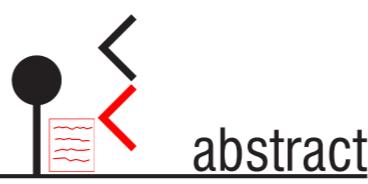
to speak through
a manuscript



to speak through
an apparatus



to read a
manuscript



To attempt to embody and replicate a spatial experience via a digitised format raises inescapable contradictions. Through the utilisation of digital media, the condition of disembodiment is unavoidable.

Whilst using the communication devices that create such ‘digital spaces’, (Zoom, Skype, Teams), the layers and barriers that exist between the user and the ‘digital space’ can be seen to cause a state of disembodiment. In doing so, this creates an experiential mode of presence that is encoded by technology. In response to this, the digital venue that will be created to house the Embodied Awareness and Space Symposium is conceived as a space through which to physically re-construct the computational processes that are embedded within digital tools such as Zoom and Skype. In doing so, the symposium constructs a critical response to the socio-political and experiential aspects that are embedded within the digital apparatus, attempting to transform the experience of disembodiment into a positive critique.

The digital means through which these shared experiences are mediated enact a series of translations that rely on languages of computation, ultimately resting on the foundation of binary operations performed by an electro-mechanical processor. As we correspond with a person, object, or drawing via the screen, we become reliant upon the media’s digital translation processes.

Our co-constitution with technology as a prosthesis, exerting agency in material and cognitive terms, is reflected in the entanglement between technology and culture. This entanglement suggests the possibility of a formal-materialist method: to explore the emergence of formal cultural ideologies that are bound with the material make-up of digital apparatus. This dual approach offers means to forensically excavate the underlying workings of digital languages as they are embedded in computational substrate. These languages may then be re-contextualised, and re-constituted through the construction of a creative practice installation, acting as a poetic critique of inherent dynamics of digital production.

Our inquiry responds to the dynamic of code, which exists both as executable text that is performed by the machine, while also holding the possibility for re-contextualisation. The fixed orthographic mark holds capacity for deferral, paradoxically enabling an ‘open’ interpretation by the reader. Extracting executable code from the machine offers the opportunity to re-work it toward an alternative, expanding the possibility for writing and interpretation – as the textuality of the writer and reader themselves is constituted by the media.

We aim to construct and explore modes of dialectical computation, developing methods of encoding that, through processes of translation and interpretation via differing media, may open up these possibilities within the previously fixed binary of digital logic.

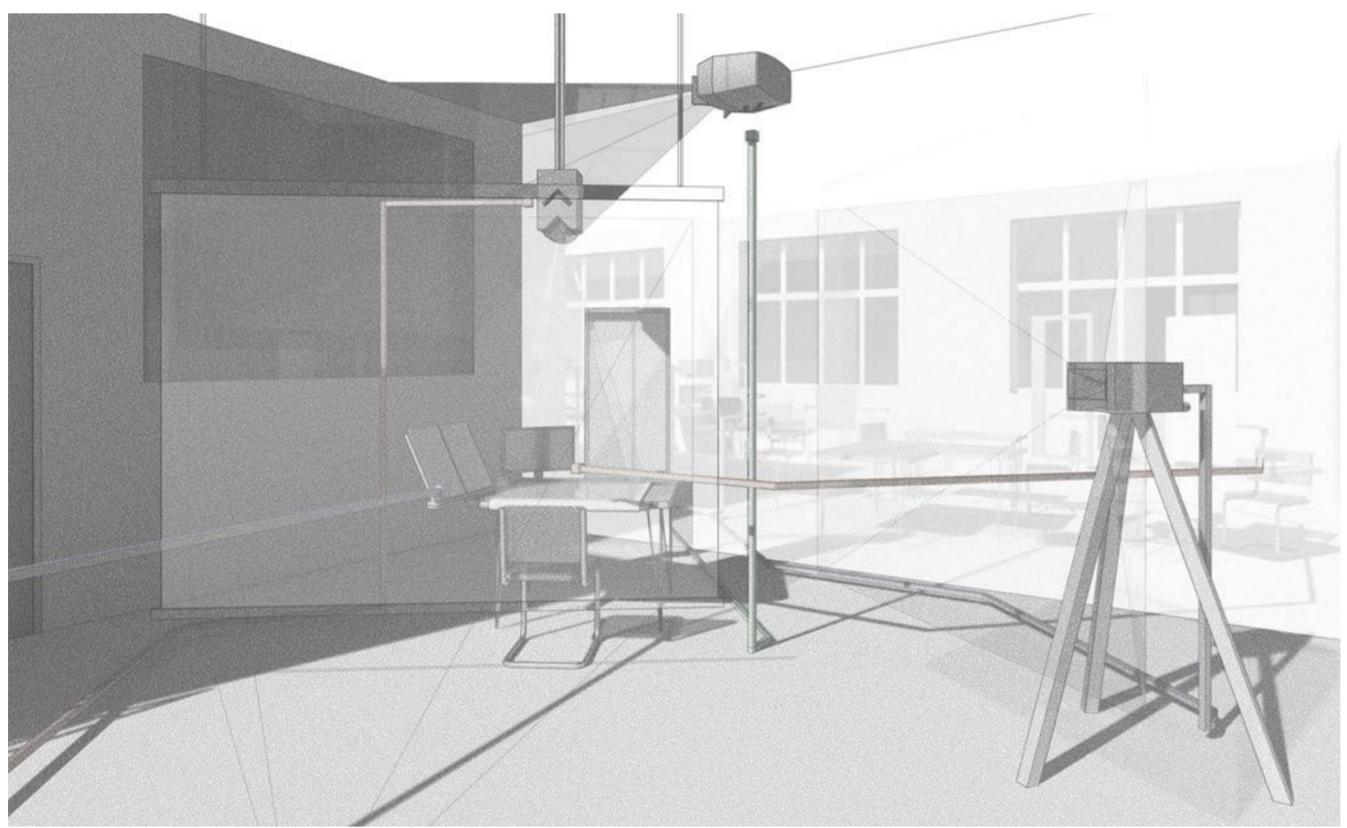
How can a user exist and navigate within two or more spaces at once? How can this be translated, projected and experienced? The intention for this project is to focus on the translation processes inherent within the dynamics of computation, by fragmenting, reconstructing, and materially inhabiting the layers that occur when such a digitally embedded experience is enacted.



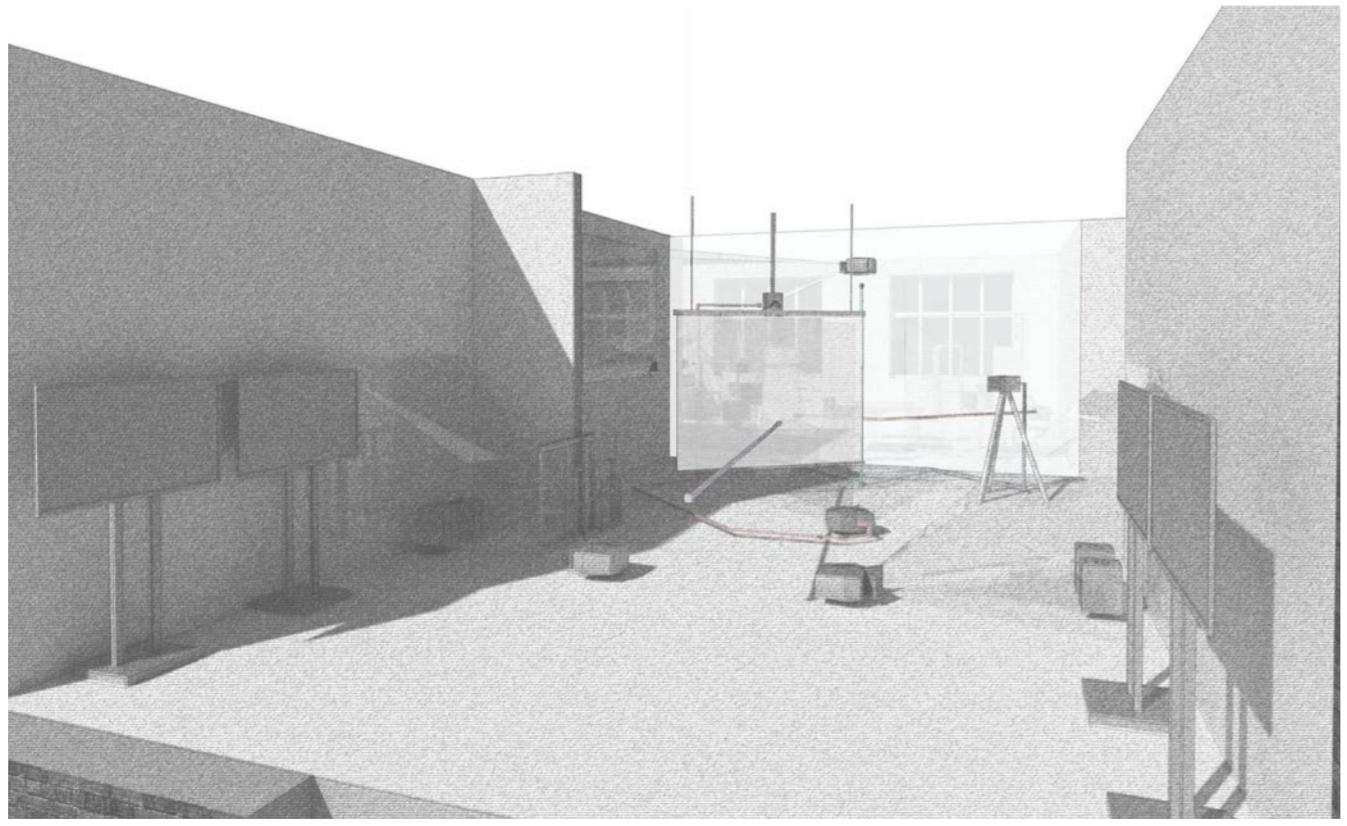
Spatial model for the dialectical computer,
developed in Autodesk Revit.



the presenter



tech 1: the translator



tech 2: the interpreter

a dialectical computer: the hybrid material/virtual venue

In re-contextualising the translation processes embedded in computation, we construct a dialectical computer to explore how they may be re-enacted and opened toward alternative ways of being.

Often within the dominant history of computation, a task is reduced to a calculable problem, encoded in an electro-mechanical apparatus that performs an automation of its processes. This may result in a reduction of difference, as the encoding of an original in according to the capacity of media catalyses a flattening of homogeneity, reshaping it according to the ontology of the machine and digital abstraction. We aim to build a system that remains open to a multiplicity of inputs and interpretations, re-contextualising the processes of computation in order to open the limits of possibility for designer and user.

the venue

The venue will form a hybrid material and virtual space where presenters can instruct a supplementary presentation to run alongside their main format, broadcast as a second feed. Comprising of two technicians, along with a set of media equipment, the dialectical computer enables the possibility of interpreting material contributed by the participants and enacting it within the space.

Our system is built as a re-construction of computational media, initially drawing from computer code. This code is recontextualised as text: an orthographic mark open to the readers interpretation and no longer subject to requirements of executability by machine.

As a starting point we utilise the C# code that forms Autodesk building modelling software, along with the html that describes webpages, and through a developing textual practice will turn them away from the machine and toward the specificity of the hybrid venue. Acknowledging the gestures, actions, instruction and performance that occurs through the lived experience of symposium.

process

Entering into dialogue with one technician, the participant may offer media including - but not limited to – text, audio, film, photographs, drawings and models which will then be interpreted and performed anew. We invite participants to contribute anything they wish to translate through this alternative form of computation. It might be a piece of work integral to their project, or an impression of the setting where they developed the work, or – reflecting on the dis-embodied nature of the conference – a reconstruction of the place they present from. The material could be left open to interpretation and reconstruction by the technicians, or more rigorously scripted in order to direct a choreographed second stream. These works and spatial experiences will be developed in dialogue with technician 1 – the translator – ahead of the event. It will then be encoded through our developing variations of code, eventually translated into instructions to be interpreted by the second technician.

Technician 1 will encode the presenter's original manuscript through iterative stages, gradually adapting the material to the apparatus in the hybrid venue. Running up to the event, a draft script will be formed that provides the basis for live coding during the symposium. This will then be re-written live and transmitted to the second technician – the interpreter – who will perform a live re-construction from the stream: adapting its content to media equipment including projectors, televisions, speakers, and methods for re-drawing/modelling.

In the manner of typical computation, which offers a graphical user interface as the primary means of input, we offer a visual account of the venue as a kit of parts to be utilised by the participant. Beyond this we have also started to script the properties of each object in the shape of object oriented coding, written in a syntax that draws from c# language. We invite participants to engage with the visual user guide (overleaf) in tandem with their own preferred methods to develop an initial manuscript.

We will also provide documentation of our initial tests in the coming weeks to illustrate the use of code, offering participants the means to write instructions directly in emerging codes if they wished.

We encourage proposals that expand the existing set of objects, or combine them in order to generate desired spatial experiences and effects.



equipment

The following equipment is available for participants to script instructions for:

primary camera for feed

(position of camera may be modified, or be choreographed to perform movement through the space through the presentation)

2 projectors

6 speakers

4 televisions

6 spotlights

8 drawing frames in various sizes (tbc)

6 podiums in various sizes (tbc)

4 12.5kg bags of clay in stone and terracotta

Building on an initial test which focusses on digital media, we will formulate means to re-create drawings and models live during the event.

timeframe

present until 31st March

At the present stage we invite participants to consider the material they wish to present in the venue, and how this could take the form of samples or spatial experiences that may be re-enacted in the venue.

1st and 2nd April

On these dates a test run will be performed to experiment with media in translation. The results and document will also be passed to participants to illustrate the possibilities and workflows emerging around the apparatus.

1st - 14th April

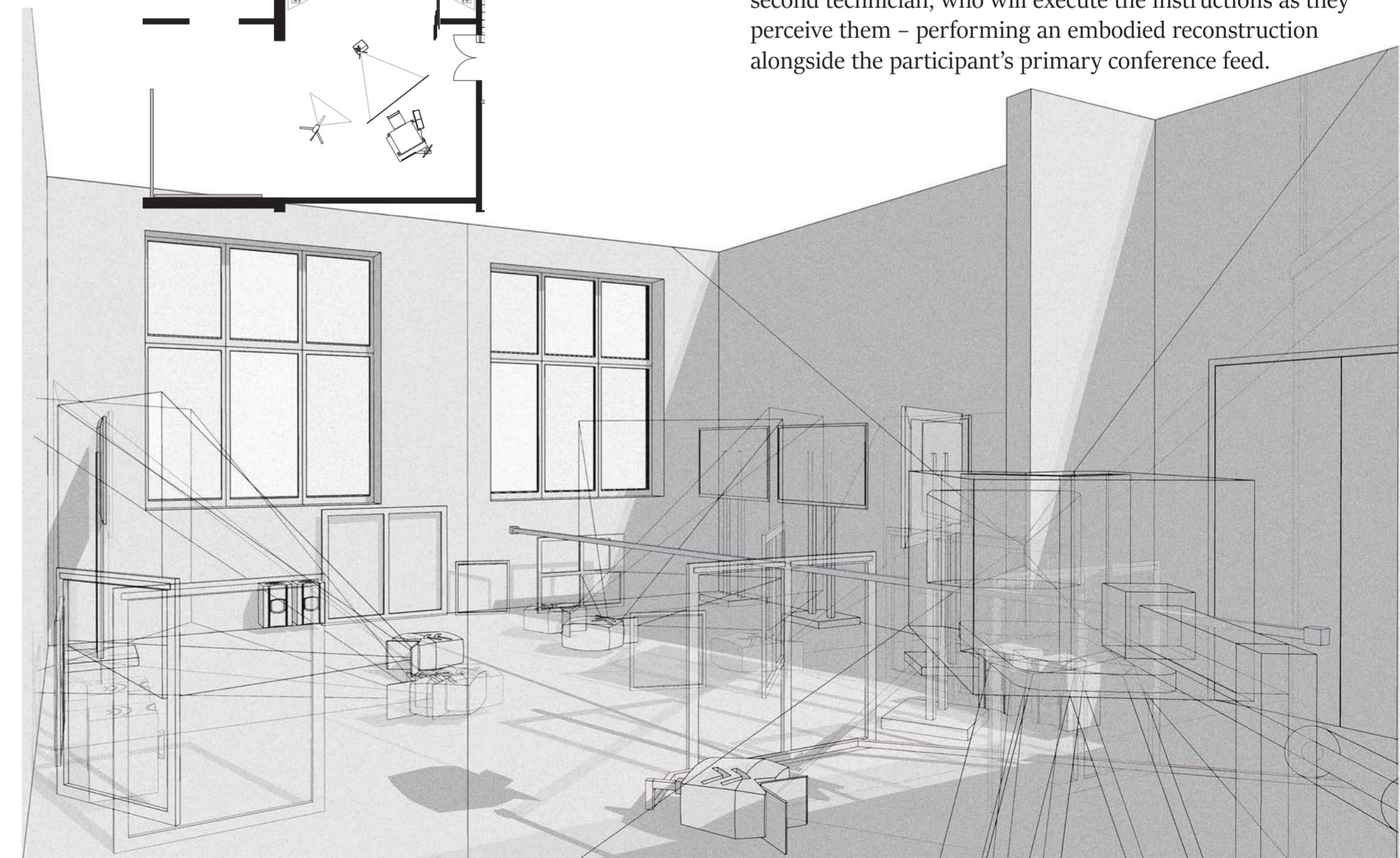
In dialogue with one technician as a translator, you can begin to formulate a draft plan for the second feed. This can take any form preferred by the author, such as a hybrid text and drawing akin to a screenplay. It may be scripted with a specific timeframe or left open for interpretation.

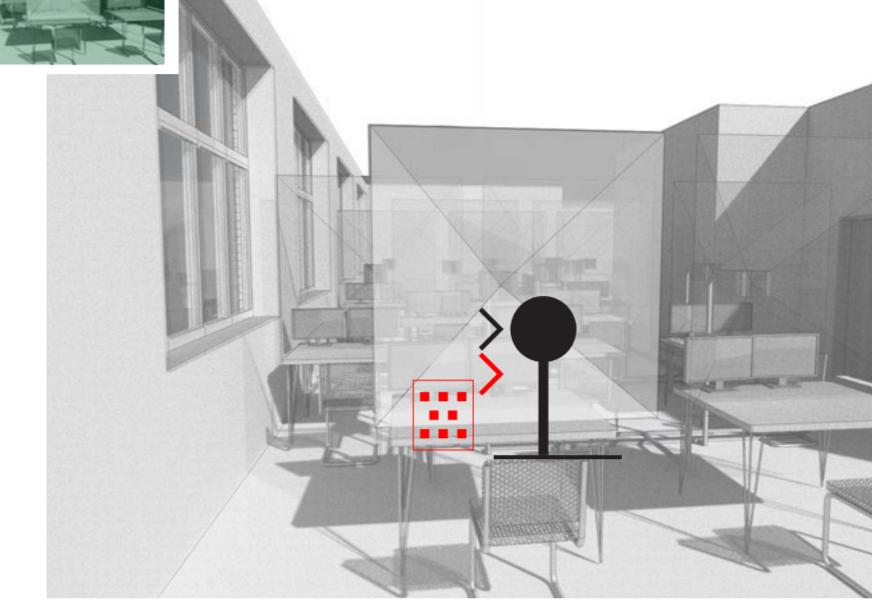
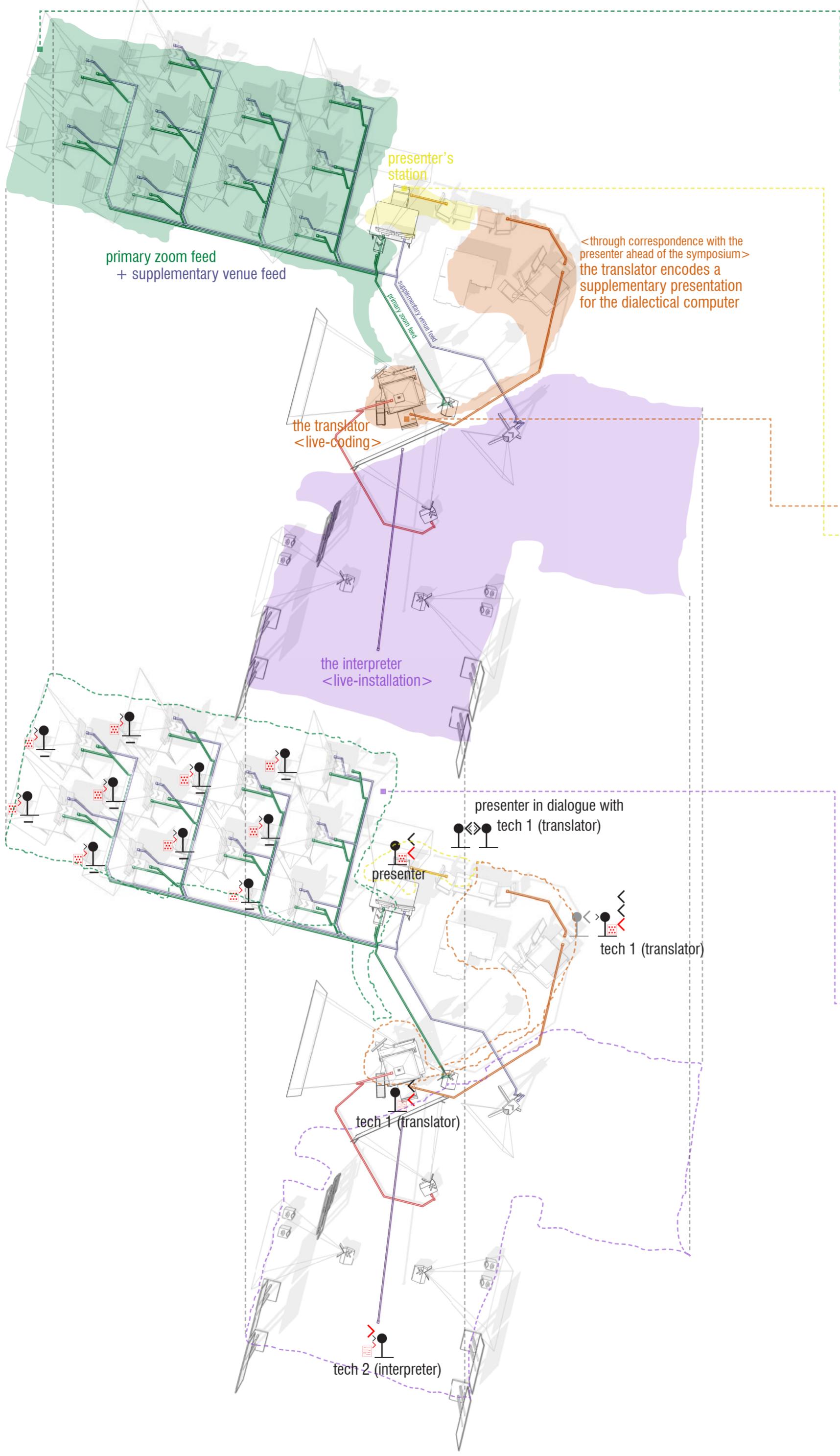
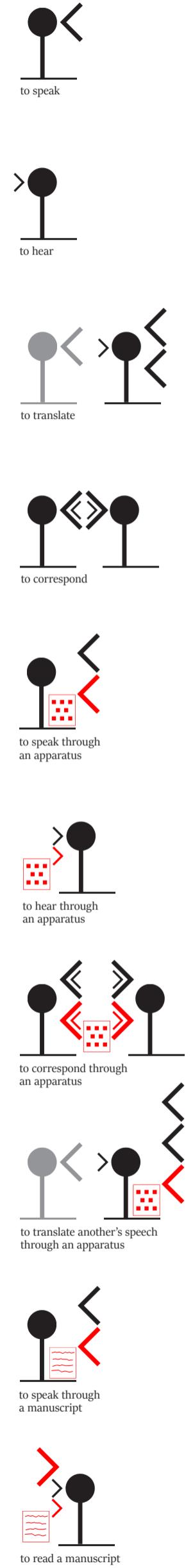
15th - 22nd April

Handover: from the complete screenplay, the translator will then complete a process of interpreting and encoding the participant's desires into our own code, to be used for communication of the performance to the second technician (the interpreter).

22nd - 24th April

The symposium: for the event, the translating technician will consult the draft material developed in dialogue with the participant, live-coding it for performance by the second technician, who will execute the instructions as they perceive them – performing an embodied reconstruction alongside the participant's primary conference feed.

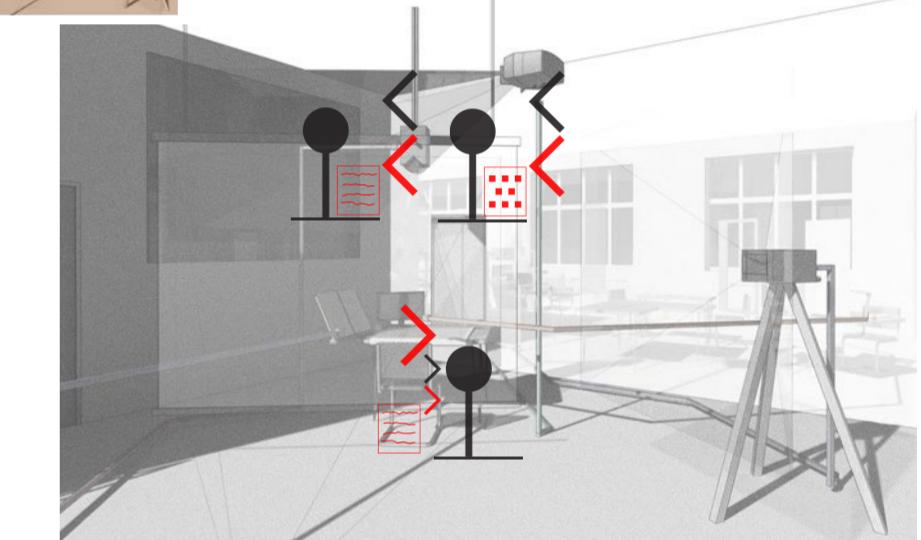




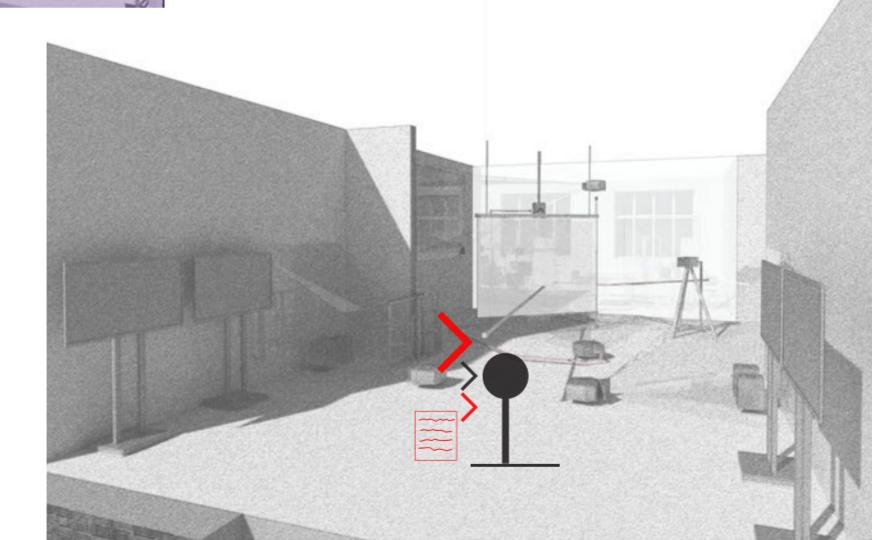
the attendee



the presenter



tech 1: the translator



tech 2: the interpreter

Appendix 1:

An initial draft of the object oriented code, forming a point of departure for the dialectical computer.

Meta-Structure

Document structure

From html

Drawing reconstruction method

Use Revit shortcuts in spatialised layout – find means to accelerate coded description for long handed reproduction by tech 2. Develop an expanded lexicon.

Meta-code

Timestamp

Digitised clock timer, minutes and seconds relative to start and end of presentation.

format = [hh:mm:ss] (double, double, double, double, double);

Time

Start

Start = Time(-- --)

End

End = Time(--,--,-)

public void Add

Summary:
Adds the specified vector to this vector and returns the result.

Parameters:

source: The vector to add to this vector.

Returns:

The vector equal to the sum of the two vectors.

Remarks:

The added vector is obtained by adding each coordinate of the specified vector to the corresponding coordinate of this vector.

Add

public Autodesk.Revit.DB.XYZ Add(Autodesk.Revit.DB.XYZ source)

public void Subtract

Subtract

public void Present

= Time(--,--,-)

public void Duration

= (TimeStart) Subtract (TimeEnd);

Is permanent? If so keep in position until end of presentation.

.toend

while.objectDuration

Semantic version:
start, end, before, during, after

Coordinate systems

class XYZ

XYZ = [XYZ] (double, double, double);

class Plane

= infinite planar object,

For orthographic:

Plane XYZ = [XYZ] (double, double, double);

For non-orthographic: [develop equation to subtract/add coordinate system according to angle]

class Axis

Axis = Plane

class Vector

Vector.Origin [XYZ] (double, double, double);

Vector.Magnitude = (double);

Vector.Bearing = (double);

Vector.End = [XYZ] (double, double, double);

Vector trueNorth = new vector;

trueNorth.Origin [XYZ] (0, 0, 0);

trueNorth.Magnitude = (∞);

trueNorth.Bearing = (0);

trueNorth.End = [XYZ] (∞ , ∞ , 0);

class Rotation

Bearing = clockwise 360°. origin at Vector trueNorth

Yaw

Roll

Axis = Plane

Bearing

EuclideanGeometry

Euclidean = [Axis X, Axis Y, Axis Z] (Plane, Plane, Plane);

Plane EuclidX = [XYZ] (X= ∞ , Y=0, Z=0);

Plane EuclidY = [XYZ] (X=0, Y= ∞ , Z=0);

Plane EuclidZ = [XYZ] (X=0, Y=0, Z= ∞);

Axis X = Plane X;

Axis Y = Plane Y;

Axis Z = Plane Z;

+ semantic description of space (between, in front of, behind...)

Venue.CoordSys = EuclideanGeometry;

* develop method to place directly in front of interpreter technician's current position

* paper relative to technician

class Interpreter

position = XYZ;

direction = rotation from Venue.CoordSys

PaperEuclid = new EuclideanGeometry;

Plane PaperEuclidX = from (paper.getsurface)

{

X = minvalue

}

Plane PaperEuclidY = from (paper.getsurface)

{

X = minvalue

}

Plane PaperEuclidZ = paper.getsurface;

PaperEuclid(PaperEuclidX, PaperEuclidY, PaperEuclidZ);

Model.CoordSys = PaperEuclid;

Axis X = Plane X;

Axis Y = Plane Y;

Axis Z = Plane Z;

ModelEuclid = new EuclideanGeometry;

Plane ModelEuclidX = [XYZ] (X= ∞ , Y=0, Z=0);

Plane ModelEuclidY = [XYZ] (X=0, Y= ∞ , Z=0);

Plane ModelEuclidZ = [XYZ] (X=0, Y=0, Z= ∞);

ModelEuclid(ModelEuclidX, ModelEuclidY, ModelEuclidZ);

Methods:

HardcodeXYZ, or get podium/worksurface reference to reset

Model.CoordSys = ModelEuclid;

Class Position

Reference origin = (string);
Position.Coord [XYZ] (double, double, double);

Object position reference

Classes:

Camera

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();

Projector

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();

Speaker

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double)

Light

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
new Drawingframe (blueDrawingframe);
new Drawingframe (redDrawingframe);
new Drawingframe (greenDrawingframe);
new Drawingframe (orangeDrawingframe);
new Drawingframe (cyanDrawingframe);
new Drawingframe (purpleDrawingframe);

Drawing

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
new Drawing (blueDrawing);
new Drawing (redDrawing);
new Drawing (greenDrawing);
new Drawing (orangeDrawing);
new Drawing (cyanDrawing);
new Drawing (purpleDrawing);

Podium

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);
new Podium (bluePodium);
new Podium (redPodium);
new Podium (greenPodium);
new Podium (orangePodium);
new Podium (cyanPodium);
new Podium (purplePodium);

Model

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);
new Model (blueModel);
new Model (redModel);
new Model (greenModel);
new Model (orangeModel);
new Model (cyanModel);
new Model (purpleModel);

Television

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);
new Time = testinstall;
testinstall.Time.Start = 00.00.00
testinstall.Time.End = 00.20.00

Text

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Drawing

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Model

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Camera

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Projector

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Speaker

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Light

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Drawingframe

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Podium

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Model

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Text

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Drawing

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Model

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Camera

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Projector

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Speaker

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Light

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Drawingframe

Position (XYZ);
Rotation (double);
Target (Position XYZ);
Start (Time);
End (Time);
Duration (Time);
Input();
Level(double);

Podium

Appendix 2

Excerpts of code used with Autodesk Revit's Application Programming Interface: a means to hardcode a model directly through text.

`U:\PM01\coding\RevitLive coding\Hardcode_dwelling_build_1\Hardcode_dwelling_build_1\Class1.cs`

```
1  using System;
2  using Autodesk.Revit.DB;
3  using Autodesk.Revit.DB.Architecture;
4  using Autodesk.Revit.DB.Selection;
5  using System.Collections.Generic;
6  using System.Diagnostics;
7  using System.IO;
8  using Autodesk.Revit.DB.Events;
9  using Autodesk.Revit.DB.Architecture;
10 using Autodesk.Revit.DB.Architecture;
11 namespace Hardcode_dwelling_build_1
12 {
13     [Autodesk.Revit.Attributes.Transaction(Autodesk.Revit.Attributes.TransactionMode.Manual)]
14     public partial class ThisDocument : IExternalObject
15     {
16         public void Module_Startup(object sender, EventArgs e)
17         {
18             // ...
19         }
20     }
21     private void Module_Shutdown(object sender, EventArgs e)
22     {
23         // ...
24     }
25 }
```

using (Transaction trans = new Transaction(doc, "Create Acoustic View"))
{
 doc.CreateView("Acoustic View");
 XYZ eye = new XYZ(0.0, 0.0, 0.0);
 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
 XYZ up = new XYZ(0.0, 1.0, 0.0);
 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
 View3D acousticView = View3D.CreateFromView(trans, viewOrientationD);
 acousticView.Name = "Acoustic View";
 acousticView.ViewTemplateId = viewTemplate.Id;
 acousticView.Commit();
}

TaskDialog.Show("stage", "Create Acoustic View");

// Create Acoustic View //

```
48     using (Transaction trans = new Transaction(doc, "Create Acoustic View"))
49     {
50         doc.CreateView("Acoustic View");
51         XYZ eye = new XYZ(0.0, 0.0, 0.0);
52         XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
53         XYZ up = new XYZ(0.0, 1.0, 0.0);
54         ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
55         View3D acousticView = View3D.CreateFromView(trans, viewOrientationD);
56         acousticView.Name = "Acoustic View";
57         acousticView.ViewTemplateId = viewTemplate.Id;
58         acousticView.Commit();
59     }
60 }
```

ViewTemplateId = new FilteredElementCollector(doc).OfClass(typeof(View))
{
 WhereElementFilter filter = new WhereElementFilter("Name == \"1 80 Aus\"");
 ViewTemplateId = filter.ExcludeElements();
}

AcousticViewTemplateId = viewTemplate.Id;

task.Commit();

TaskDialog.Show("stage", "Create Acoustic View");

// Create levels //

```
61     using (Transaction transLevel = new Transaction(doc, "Create levels"))
62     {
63         doc.CreateView("Level");
64         XYZ start = new XYZ(0.0, 0.0, 0.0);
65         XYZ end = new XYZ(0.0, 0.0, 0.0);
66         LevelFoundationName = "levelFoundation";
67         LevelFlooringName = "levelFlooring";
68         LevelRoofName = "levelRoof";
69         levelFoundation = Level.Create(doc, start, end, levelFoundationName);
70         levelFlooring = Level.Create(doc, start, end, levelFlooringName);
71         levelRoof = Level.Create(doc, start, end, levelRoofName);
72         levelRoof.Commit();
73     }
74 }
```

TaskDialog.Show("stage", "Create Levels");

// Create levels //

```
75     using (Transaction transLevel = new Transaction(doc, "Create levels"))
76     {
77         doc.CreateView("Level");
78         XYZ start = new XYZ(0.0, 0.0, 0.0);
79         XYZ end = new XYZ(0.0, 0.0, 0.0);
80         LevelFoundationName = "levelFoundation";
81         LevelFlooringName = "levelFlooring";
82         LevelRoofName = "levelRoof";
83         levelFoundation = Level.Create(doc, start, end, levelFoundationName);
84         levelFlooring = Level.Create(doc, start, end, levelFlooringName);
85         levelRoof = Level.Create(doc, start, end, levelRoofName);
86         levelRoof.Commit();
87     }
88 }
```

TaskDialog.Show("stage", "Create Levels");

// Create Plan Views //

```
89     using (Transaction transPlan = new Transaction(doc, "Create Plan View"))
90     {
91         doc.CreateView("Plan");
92         XYZ eye = new XYZ(0.0, 0.0, 0.0);
93         XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
94         XYZ up = new XYZ(0.0, 1.0, 0.0);
95         ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
96         View3D planView = View3D.CreateFromView(transPlan, viewOrientationD);
97         planView.Name = "Plan View";
98         planView.ViewTemplateId = viewTemplate.Id;
99         planView.Commit();
100    }
101 }
```

TaskDialog.Show("stage", "Create Plan View");

// Create Plan Views //

```
102     using (Transaction transPlan = new Transaction(doc, "Create Plan View"))
103     {
104         doc.CreateView("Plan");
105         XYZ eye = new XYZ(0.0, 0.0, 0.0);
106         XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
107         XYZ up = new XYZ(0.0, 1.0, 0.0);
108         ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
109         View3D planView = View3D.CreateFromView(transPlan, viewOrientationD);
110         planView.Name = "Plan View";
111         planView.ViewTemplateId = viewTemplate.Id;
112         planView.Commit();
113     }
114 }
```

TaskDialog.Show("stage", "Create Plan View");

// Create Section Views //

115 using (Transaction transSection = new Transaction(doc, "Create Section View"))
116 {
117 doc.CreateView("Section");
118 XYZ eye = new XYZ(0.0, 0.0, 0.0);
119 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
120 XYZ up = new XYZ(0.0, 1.0, 0.0);
121 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
122 View3D sectionView = View3D.CreateFromView(transSection, viewOrientationD);
123 sectionView.Name = "Section View";
124 sectionView.ViewTemplateId = viewTemplate.Id;
125 sectionView.Commit();
126 }
127 }

TaskDialog.Show("stage", "Create Section View");

// Create Section Views //

128 using (Transaction transSection = new Transaction(doc, "Create Section View"))
129 {
130 doc.CreateView("Section");
131 XYZ eye = new XYZ(0.0, 0.0, 0.0);
132 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
133 XYZ up = new XYZ(0.0, 1.0, 0.0);
134 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
135 View3D sectionView = View3D.CreateFromView(transSection, viewOrientationD);
136 sectionView.Name = "Section View";
137 sectionView.ViewTemplateId = viewTemplate.Id;
138 sectionView.Commit();
139 }
140 }

TaskDialog.Show("stage", "Create Section View");

// Create Internal Walls at Ground Floor Level //

141 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
142 {
143 doc.CreateView("Internal Walls");
144 XYZ eye = new XYZ(0.0, 0.0, 0.0);
145 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
146 XYZ up = new XYZ(0.0, 1.0, 0.0);
147 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
148 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
149 internalWalls.Name = "Internal Walls";
150 internalWalls.ViewTemplateId = viewTemplate.Id;
151 internalWalls.Commit();
152 }
153 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

154 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
155 {
156 doc.CreateView("Internal Walls");
157 XYZ eye = new XYZ(0.0, 0.0, 0.0);
158 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
159 XYZ up = new XYZ(0.0, 1.0, 0.0);
160 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
161 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
162 internalWalls.Name = "Internal Walls";
163 internalWalls.ViewTemplateId = viewTemplate.Id;
164 internalWalls.Commit();
165 }
166 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

167 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
168 {
169 doc.CreateView("Internal Walls");
170 XYZ eye = new XYZ(0.0, 0.0, 0.0);
171 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
172 XYZ up = new XYZ(0.0, 1.0, 0.0);
173 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
174 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
175 internalWalls.Name = "Internal Walls";
176 internalWalls.ViewTemplateId = viewTemplate.Id;
177 internalWalls.Commit();
178 }
179 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

180 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
181 {
182 doc.CreateView("Internal Walls");
183 XYZ eye = new XYZ(0.0, 0.0, 0.0);
184 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
185 XYZ up = new XYZ(0.0, 1.0, 0.0);
186 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
187 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
188 internalWalls.Name = "Internal Walls";
189 internalWalls.ViewTemplateId = viewTemplate.Id;
190 internalWalls.Commit();
191 }
192 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

193 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
194 {
195 doc.CreateView("Internal Walls");
196 XYZ eye = new XYZ(0.0, 0.0, 0.0);
197 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
198 XYZ up = new XYZ(0.0, 1.0, 0.0);
199 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
200 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
201 internalWalls.Name = "Internal Walls";
202 internalWalls.ViewTemplateId = viewTemplate.Id;
203 internalWalls.Commit();
204 }
205 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

206 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
207 {
208 doc.CreateView("Internal Walls");
209 XYZ eye = new XYZ(0.0, 0.0, 0.0);
210 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
211 XYZ up = new XYZ(0.0, 1.0, 0.0);
212 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
213 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
214 internalWalls.Name = "Internal Walls";
215 internalWalls.ViewTemplateId = viewTemplate.Id;
216 internalWalls.Commit();
217 }
218 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

219 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
220 {
221 doc.CreateView("Internal Walls");
222 XYZ eye = new XYZ(0.0, 0.0, 0.0);
223 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
224 XYZ up = new XYZ(0.0, 1.0, 0.0);
225 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
226 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
227 internalWalls.Name = "Internal Walls";
228 internalWalls.ViewTemplateId = viewTemplate.Id;
229 internalWalls.Commit();
230 }
231 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

232 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
233 {
234 doc.CreateView("Internal Walls");
235 XYZ eye = new XYZ(0.0, 0.0, 0.0);
236 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
237 XYZ up = new XYZ(0.0, 1.0, 0.0);
238 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
239 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
240 internalWalls.Name = "Internal Walls";
241 internalWalls.ViewTemplateId = viewTemplate.Id;
242 internalWalls.Commit();
243 }
244 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

245 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
246 {
247 doc.CreateView("Internal Walls");
248 XYZ eye = new XYZ(0.0, 0.0, 0.0);
249 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
250 XYZ up = new XYZ(0.0, 1.0, 0.0);
251 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
252 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
253 internalWalls.Name = "Internal Walls";
254 internalWalls.ViewTemplateId = viewTemplate.Id;
255 internalWalls.Commit();
256 }
257 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

258 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
259 {
260 doc.CreateView("Internal Walls");
261 XYZ eye = new XYZ(0.0, 0.0, 0.0);
262 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
263 XYZ up = new XYZ(0.0, 1.0, 0.0);
264 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
265 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
266 internalWalls.Name = "Internal Walls";
267 internalWalls.ViewTemplateId = viewTemplate.Id;
268 internalWalls.Commit();
269 }
270 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

271 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
272 {
273 doc.CreateView("Internal Walls");
274 XYZ eye = new XYZ(0.0, 0.0, 0.0);
275 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
276 XYZ up = new XYZ(0.0, 1.0, 0.0);
277 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
278 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
279 internalWalls.Name = "Internal Walls";
280 internalWalls.ViewTemplateId = viewTemplate.Id;
281 internalWalls.Commit();
282 }
283 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

284 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
285 {
286 doc.CreateView("Internal Walls");
287 XYZ eye = new XYZ(0.0, 0.0, 0.0);
288 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
289 XYZ up = new XYZ(0.0, 1.0, 0.0);
290 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
291 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
292 internalWalls.Name = "Internal Walls";
293 internalWalls.ViewTemplateId = viewTemplate.Id;
294 internalWalls.Commit();
295 }
296 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

297 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
298 {
299 doc.CreateView("Internal Walls");
300 XYZ eye = new XYZ(0.0, 0.0, 0.0);
301 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
302 XYZ up = new XYZ(0.0, 1.0, 0.0);
303 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
304 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
305 internalWalls.Name = "Internal Walls";
306 internalWalls.ViewTemplateId = viewTemplate.Id;
307 internalWalls.Commit();
308 }
309 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

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311 {
312 doc.CreateView("Internal Walls");
313 XYZ eye = new XYZ(0.0, 0.0, 0.0);
314 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
315 XYZ up = new XYZ(0.0, 1.0, 0.0);
316 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
317 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
318 internalWalls.Name = "Internal Walls";
319 internalWalls.ViewTemplateId = viewTemplate.Id;
320 internalWalls.Commit();
321 }
322 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

323 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
324 {
325 doc.CreateView("Internal Walls");
326 XYZ eye = new XYZ(0.0, 0.0, 0.0);
327 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
328 XYZ up = new XYZ(0.0, 1.0, 0.0);
329 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
330 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
331 internalWalls.Name = "Internal Walls";
332 internalWalls.ViewTemplateId = viewTemplate.Id;
333 internalWalls.Commit();
334 }
335 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

336 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
337 {
338 doc.CreateView("Internal Walls");
339 XYZ eye = new XYZ(0.0, 0.0, 0.0);
340 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
341 XYZ up = new XYZ(0.0, 1.0, 0.0);
342 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
343 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
344 internalWalls.Name = "Internal Walls";
345 internalWalls.ViewTemplateId = viewTemplate.Id;
346 internalWalls.Commit();
347 }
348 }

TaskDialog.Show("stage", "Create Internal Walls at Ground Floor Level");

// Create Internal Walls at Ground Floor Level //

349 using (Transaction transInternalWalls = new Transaction(doc, "Create Internal Walls at Ground Floor Level"))
350 {
351 doc.CreateView("Internal Walls");
352 XYZ eye = new XYZ(0.0, 0.0, 0.0);
353 XYZ lookAt = new XYZ(0.0, 0.0, 0.0);
354 XYZ up = new XYZ(0.0, 1.0, 0.0);
355 ViewOrientation3D viewOrientationD = new ViewOrientation3D(eye, lookAt, up);
356 View3D internalWalls = View3D.CreateFromView(transInternalWalls, viewOrientationD);
357 internalWalls.Name = "Internal Walls";
358 internalWalls.ViewTemplateId = viewTemplate.Id;
359 internalWalls.Commit();
360 }
361 }</pre

